

ECE 329 – Fall 2022

Prof. Ravaioli – Office: 2062 ECEB

Section E – 1:00pm

Lecture 16

Lecture 16 – Outline

- Inductance
- The Shorted Capacitor
- Charge conservation and the continuity equation
- Displacement current

Reading assignment

Prof. Kudeki's ECE 329 Lecture Notes on Fields and Waves:

- 16) Charge conservation, continuity equation, displacement current, Maxwell's equations

We have defined the magnetic flux as

$$\Psi = \int_S \mathbf{B} \cdot d\mathbf{s} \quad (\text{Wb})$$

For a single loop carrying a current I , if we assume a linear relationship the ratio between flux and current is a constant. The ratio is called **self-inductance**

$$L = \frac{\Psi}{I}$$

For a solenoid with n loops, the self-inductance is

flux of a single loop

$$L \equiv \frac{n\Psi}{I}$$

From Lecture 13 – Determine the magnetic field of an infinite solenoid with N loops per unit length (counterclockwise as seen from the top), stacked in the z -direction, each carrying current I .

With tight winding, thin wires and infinite length we may assume:

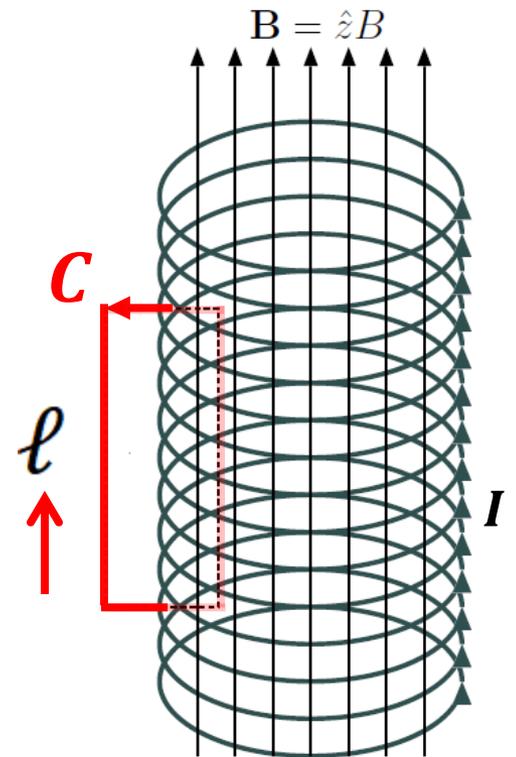
- $\mathbf{B} = 0$ outside the solenoid
- \mathbf{B} independent of z inside the solenoid

$$\oint_C \mathbf{B} \cdot d\mathbf{l} = \mu_0 I_C \Rightarrow \ell B = \mu_0 I N \ell$$

$$B = \mu_0 I N$$

$$\mathbf{H} = \hat{z} I N$$

↑
current loops per meter



To generalize, the self-inductance is the ratio

$$L = \frac{\text{total concatenated magnetic flux}}{\text{current}}$$

For a **long solenoid** aligned along the z -axis, we can assume constant interior magnetic induction density

$$\mathbf{B} = \mu_0 I N \hat{z}$$

↑
loops per unit length

If the solenoid has length ℓ and cross-sectional area A

$$L = \frac{n\Psi}{I} = \frac{\overbrace{N\ell}^{\text{total number of loops } n} (\mu_0 I N) A}{I} = \overbrace{N^2 \mu_0 A \ell}^{\text{inductance depends only on geometry and material}}$$

We have also seen that variation of the flux induces *emf*

$$\mathcal{E} = -\frac{d\Psi}{dt}$$

flux of a
single loop

For a solenoid with n loops $LI = n\Psi$

$$\mathcal{E} = -\frac{d}{dt}n\Psi \equiv -L\frac{dI}{dt}$$

$$\mathcal{E} = -\underbrace{N^2\mu_o A\ell}_L \frac{dI}{dt} = -\underbrace{\frac{n^2}{\ell}\mu_o A}_L \frac{dI}{dt}$$

If the solenoid has resistance R and is conducting a current I then we can write

$$\mathcal{E} = -L \frac{dI}{dt}$$

emf

voltage
drop



$$\mathcal{E} = RI$$

$$-L \frac{dI}{dt} = RI$$

So, the following differential equation describes the behavior of a solenoid circuit

$$\frac{dI}{dt} + \frac{R}{L}I = 0$$

A solenoid inductor, connected to an external circuit with a “quasi-static” (size \ll smallest wavelength in the signal) current I , develops a voltage drop across its terminals

$$V = L \frac{dI}{dt}$$

The instantaneous power absorbed is

$$P = VI = L \frac{dI}{dt} I = \frac{d}{dt} \left(\frac{1}{2} LI^2 \right)$$

The stored energy is

$$B = \mu_0 IN$$

$$W = \frac{1}{2} LI^2 = \frac{1}{2} \underbrace{N^2 \mu_0 A \ell}_{L} I^2 = \frac{|B_z|^2}{2\mu_0} A \ell = \frac{1}{2} \mu_0 |H_z|^2 A \ell$$

$$W = \frac{1}{2} \mu_o |H_z|^2 \underbrace{A\ell}_{\text{volume}}$$

stored magnetic energy

per unit volume w

In general

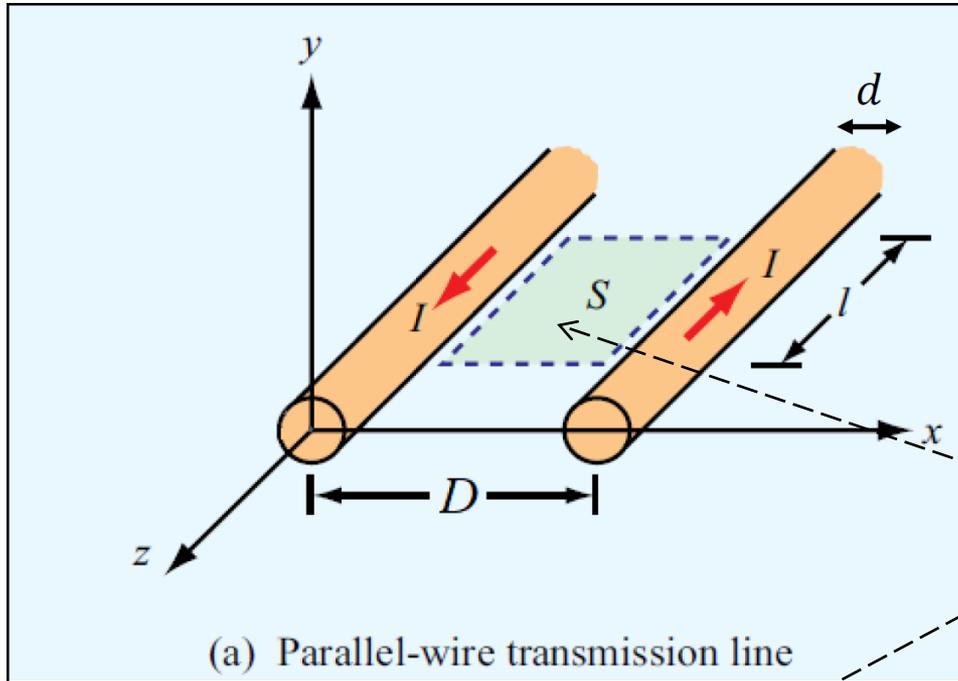
$$w = \frac{1}{2} \mu_o \mathbf{H} \cdot \mathbf{H}$$

For a material medium, we will see later that

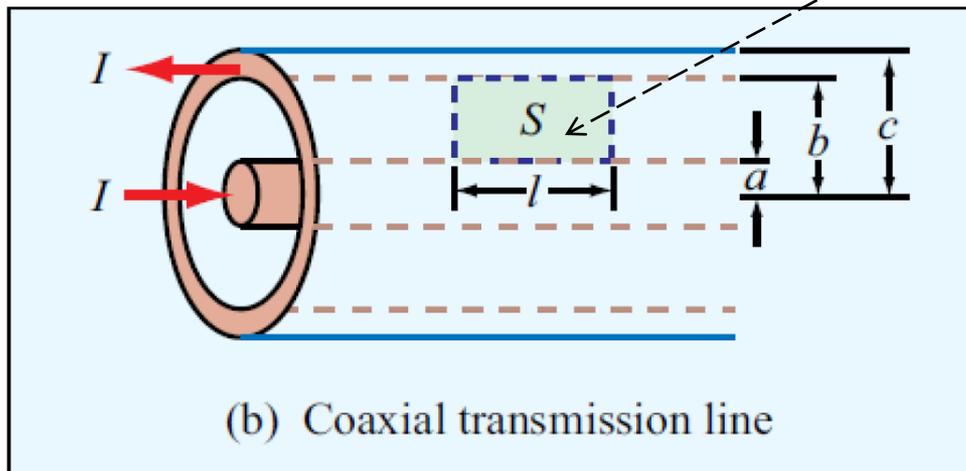
$$\mu = (1 + \chi_m) \mu_o$$

↑
magnetic
susceptibility

Structures consisting of separate conductors can also couple with magnetic fields and exhibit inductance

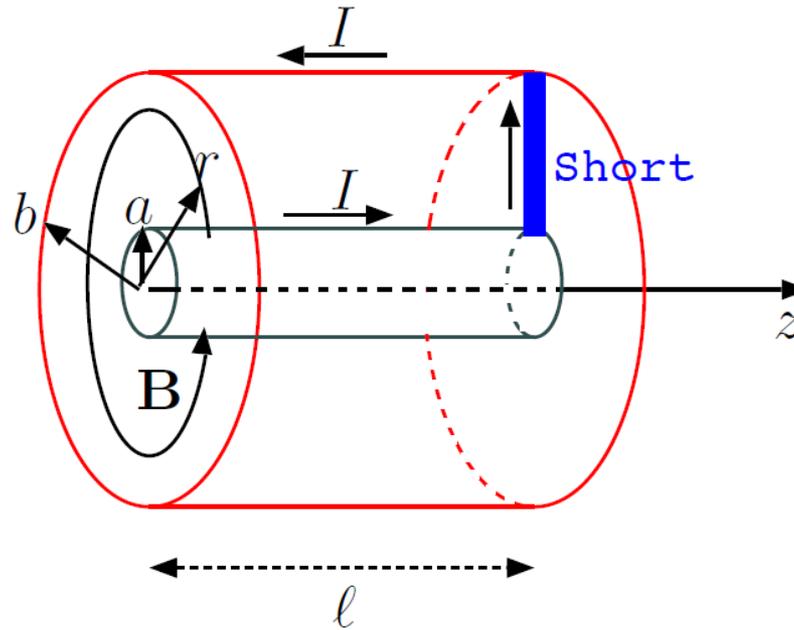


To compute the inductance per unit length of a two-conductor transmission line, we need to determine the magnetic flux through the area S between the conductors.



Inductance and capacitance per unit length will be extremely important for the study of transmission lines based on configurations with multiple conductors.

Inductance of shorted coaxial cable

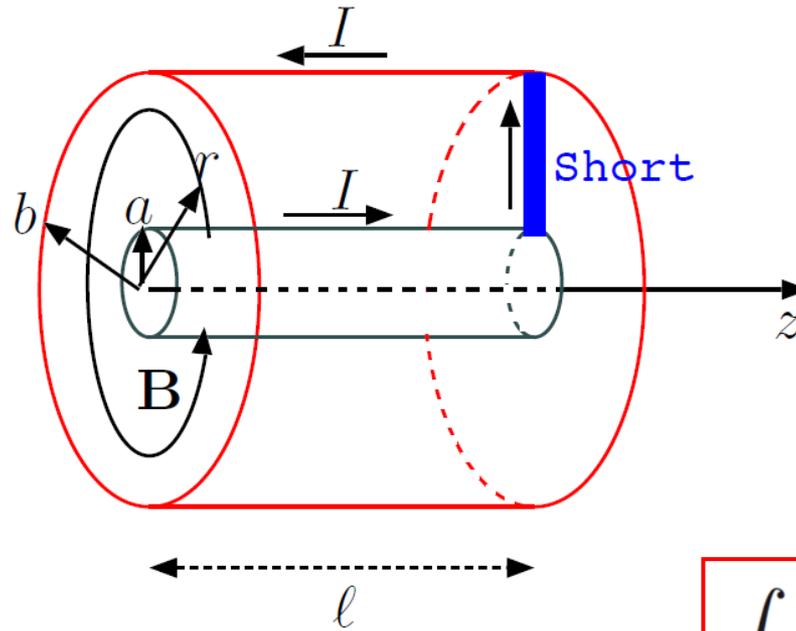


$$l \gg b$$

approximation of field behavior as in an infinite coaxial cable is acceptable

The magnetic field wraps around the inner conductor and is constant for a certain radius r at any azimuthal angle

Invoking Ampere's Law



$$\oint_C \mathbf{B} \cdot d\mathbf{l} = \mu_0 I_C$$

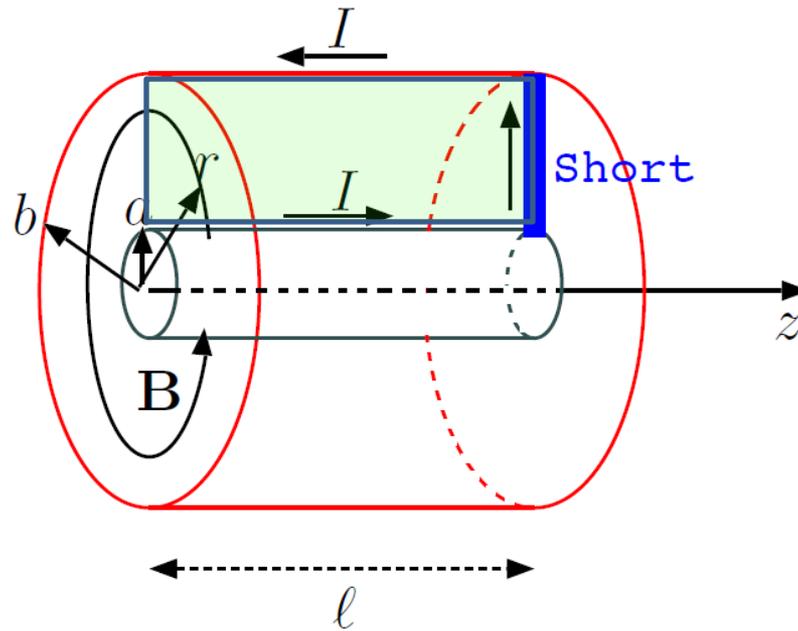
$$\oint_C \mathbf{H} \cdot d\mathbf{l} = I_C$$

integral form of Ampere's Law

$$r > a$$

$$B_\phi 2\pi r = \mu_0 I \Rightarrow B_\phi = \frac{\mu_0 I}{2\pi r}$$

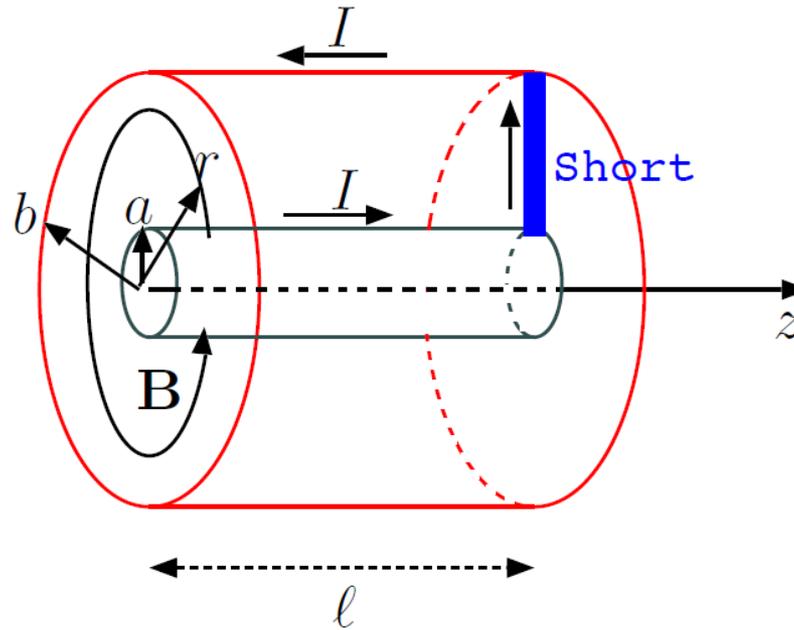
From the Magnetic Flux linked with a closed current path



$$\Psi = \int_S \mathbf{B} \cdot d\mathbf{S} = \ell \frac{\mu_0}{2\pi} I \int_a^b \frac{dr}{r} = \ell \frac{\mu_0}{2\pi} \ln \frac{b}{a} I$$

$$\Psi = LI \quad \boxed{L \equiv \frac{\ell \mu_0}{2\pi} \ln \frac{b}{a}}$$

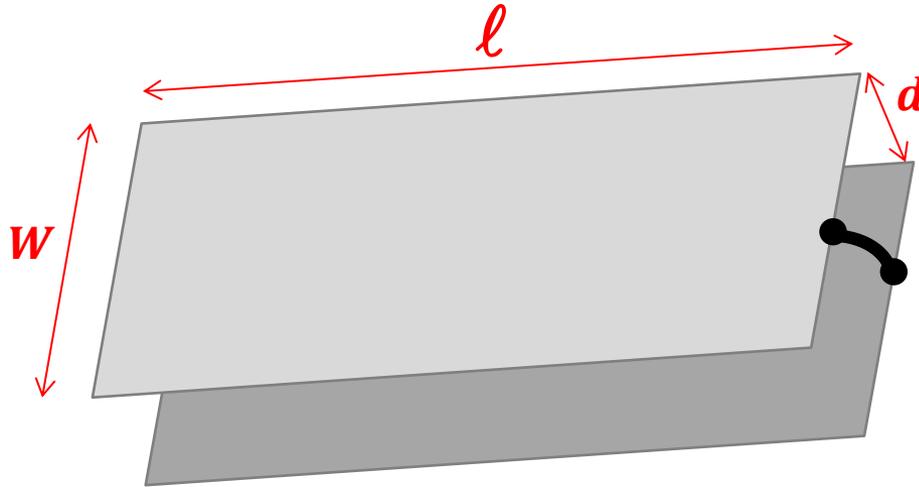
Inductance and Capacitance per unit length



$$\mathcal{L} = \frac{\ln \frac{b}{a}}{2\pi} \mu_0$$

$$\mathcal{C} = \frac{2\pi}{\ln \frac{b}{a}} \epsilon_0$$

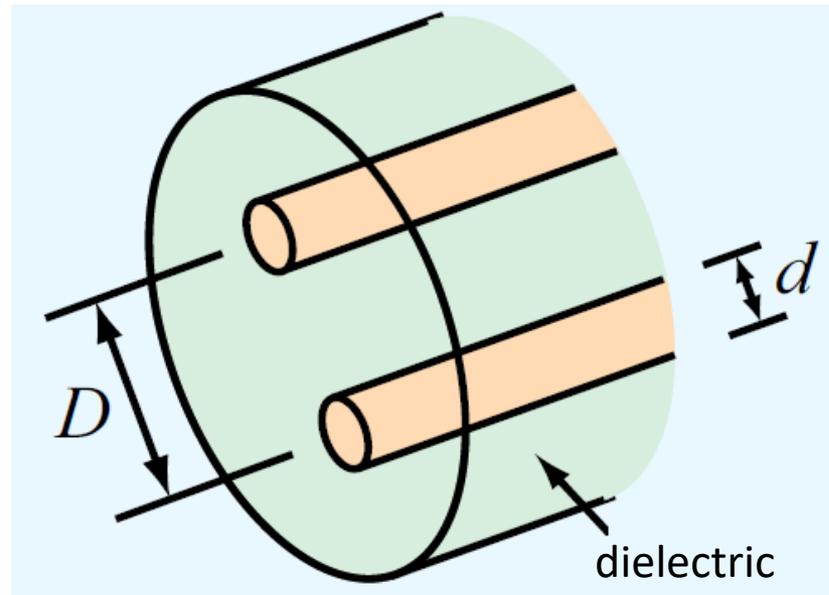
Inductance and Capacitance per unit length of Shorted Parallel Plates



$$\mathcal{L} = \frac{d}{W} \mu_0$$

$$\mathcal{C} = \frac{W}{d} \epsilon_0$$

Inductance and Capacitance per unit length of Shorted Parallel Wires



$$\mathcal{L} = \frac{\mu}{\pi} \ln \left[(D/d) + \sqrt{(D/d)^2 - 1} \right]$$

$$\mathcal{C} = \frac{\pi \epsilon}{\ln \left[(D/d) + \sqrt{(D/d)^2 - 1} \right]}$$

In general, total electric charge is conserved.

Processes which create excess charge of a given polarity in a certain region of space will create charge of opposite polarity somewhere else.

Similarly, disappearance of a charge implies that a charge of opposite polarity disappears as well. Types of phenomena found in nature are:

Generation – an electron leaves an atom (or a molecule) due to an external excitation (thermal, photonic or other kind of ionizing irradiation, electrical breakdown,...)

Recombination – an ion and an electron join together to produce a neutral atom (or molecule)

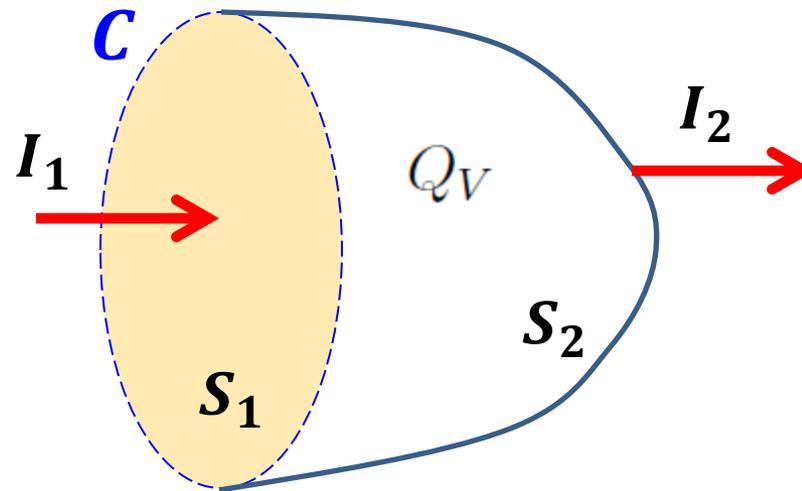
Annihilation – For example, a positron and an electron recombine generating a pair of gamma rays (high energy photons)

Transport phenomena may separate the charges and create regions of charge imbalance. This process is described by electrical current flow.

Imagine that a certain volume V is delimited by two surfaces sharing the same contour

free charge in volume V

$$Q_V = \int_V \rho dV$$



Current in

$$I_1 = \int_{S_1} \mathbf{J} \cdot d\mathbf{S}_1$$

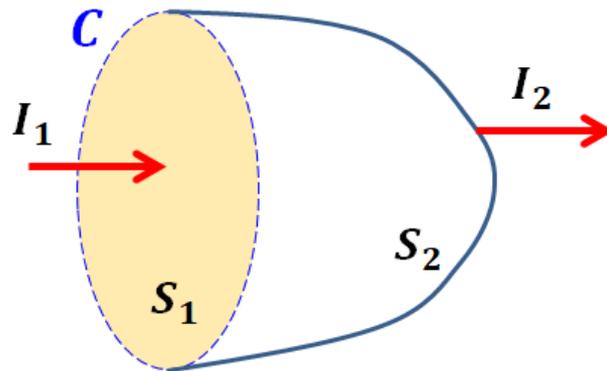
Current out

$$I_2 = \int_{S_2} \mathbf{J} \cdot d\mathbf{S}_2$$

If $I_1 \neq I_2$ the net charge Q_V contained in volume V changes at a rate

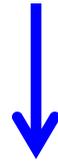
$$\frac{dQ_V}{dt} = I_1 - I_2$$

$$\frac{d}{dt} \int_V \rho dV = \int_{S_1} \mathbf{J} \cdot d\mathbf{S}_1 - \int_{S_2} \mathbf{J} \cdot d\mathbf{S}_2$$



With $\mathcal{S} = \mathcal{S}_1 + \mathcal{S}_2$ forming a closed surface

$$\frac{d}{dt} \int_V \rho dV = \int_{S_1} \mathbf{J} \cdot d\mathbf{S}_1 - \int_{S_2} \mathbf{J} \cdot d\mathbf{S}_2$$



$$\int_V \frac{\partial \rho}{\partial t} dV = - \oint_S \mathbf{J} \cdot d\mathbf{S}$$

Integral form of the continuity equation

Divergence Theorem

$$\oint_S \mathbf{J} \cdot d\mathbf{S} = \int_V \nabla \cdot \mathbf{J} dV$$

$$\int_V \frac{\partial \rho}{\partial t} dV = - \int_V \nabla \cdot \mathbf{J} dV$$

Differential form of the continuity equation

→
$$\frac{\partial \rho}{\partial t} = - \nabla \cdot \mathbf{J}$$

This is a balance equation which accounts for charge conservation when charge density varies in space due to current flow.

Displacement Current

Electrostatics

Electrodynamics

$$\nabla \times \mathbf{E} = 0 \quad \longrightarrow \quad \nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

A time-varying B induces a time-varying E through Faraday's law

Magnetostatics

Electrodynamics

$$\nabla \times \mathbf{H} = \mathbf{J} \quad \longrightarrow \quad ?$$

How do we extend Ampere's law to the case of time-varying E ?

One could observe that

$$\mathbf{J} = \sigma \mathbf{E}$$

but this essentially describes a quasi-static regime where local steady-state is quickly reached.

What if charges of different polarity are separated, for instance, and also react differently to a varying electric field due to inertia?

Maxwell postulated that, to guarantee charge conservation, Ampere's law should be rewritten as

$$\nabla \times \mathbf{H} = \mathbf{J} + \underbrace{\frac{\partial \mathbf{D}}{\partial t}}$$

displacement current density

Verification: Take the divergence of modified Ampere's law

$$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$$

$$\underbrace{\nabla \cdot (\nabla \times \mathbf{H})}_{\text{divergence of a curl is zero}} = \nabla \cdot \mathbf{J} + \frac{\partial}{\partial t} \nabla \cdot \mathbf{D} = 0$$

Current continuity was obtained as

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \mathbf{J} = 0$$

and if we assume Gauss law to remain valid in non-equilibrium

$$\nabla \cdot \mathbf{D} = \rho \quad \longrightarrow \quad \frac{\partial}{\partial t} \nabla \cdot \mathbf{D} = \frac{\partial \rho}{\partial t}$$

Ampere's law as modified is consistent with charge conservation

Time-varying electromagnetic fields obey this set of laws

$$\nabla \cdot \mathbf{D} = \rho \quad \text{Gauss's law}$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad \text{Faraday's law}$$

$$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \quad \text{Ampere's law}$$

with constitutive equations

$$\mathbf{D} = \epsilon \mathbf{E} \quad \mathbf{B} = \mu \mathbf{H}$$

This is the complete set of Maxwell's equations

$\nabla \cdot \mathbf{B} = 0$ remains valid as a consequence of Faraday's law

This can be shown by taking the divergence

$$\nabla \cdot (\nabla \times \mathbf{E}) = -\frac{\partial}{\partial t} \nabla \cdot \mathbf{B} = 0$$

But do magnetic monopoles exist or not? They have never been observed but modern unified theories, like *String Theory* and others, all actually require the existence of magnetic monopoles... and the search continues.

For a quick summary, you can read these posts:

<https://home.cern/news/opinion/experiments/observation-authentic-make-believe-monopoles>

<https://home.cern/news/news/physics/atlas-homes-magnetic-monopoles>

Now that we have the complete set of Maxwell's equations, we can state the complete boundary conditions at interfaces

$$\hat{n} \cdot (\mathbf{D}^+ - \mathbf{D}^-) = \rho_s$$

$$\hat{n} \cdot (\mathbf{B}^+ - \mathbf{B}^-) = 0$$

$$\hat{n} \times (\mathbf{E}^+ - \mathbf{E}^-) = 0$$

$$\hat{n} \times (\mathbf{H}^+ - \mathbf{H}^-) = \mathbf{J}_s$$

what is this?



The parallel-plate capacitor is a good example to illustrate the physical meaning of displacement current

$$V_s(t) = V_0 \cos \omega t \quad (\text{V})$$

$$\mathbf{E} = \hat{y} \frac{V_c}{d} = \hat{y} \frac{V_0}{d} \cos \omega t$$

Module 6.3 **Displacement Current**

$t = 0.108T + 1T$ $\omega t = 39^\circ + 2\pi$

START

STOP

Instructions

Reset

Surfaces

I_{1c}

→

$C = \epsilon_0 \epsilon_r (l \times w) / d$

$I_{1c} = I_{3c} = I_{2d}$

Input

Frequency $f =$ Hz

Dielectric Permittivity $\epsilon_r =$

Voltage Amplitude $V_0 =$ V

Plates Separation $d =$ m

Length of Plates $l =$ m

Width of Plates $w =$ m

Output

Impedance

$Z = R + jX = 0.0 - j(\omega C)^{-1}$
 $= 0.0 - j 450.0 [\Omega]$

Capacitance

$C = 353.68 \times 10^{-15} [\text{F}]$

Surface charge density on plates

$Q_S = 3.54 \times 10^{-9} \cos(\omega t) [\text{C} / \text{m}^2]$

Voltage

$\tilde{V}_S(t) = 1.0 \cos(\omega t) [\text{V}]$

Displacement Current

$\tilde{I}_{2d}(t) = -0.002222 \sin(\omega t) [\text{A}]$

The parallel-plate capacitor is a good example to illustrate the physical meaning of displacement current

$$V_s(t) = V_0 \cos \omega t \quad (\text{V})$$

$$C = \epsilon A / d$$

In the perfectly conducting wires there is only conduction current and no displacement current because the fields are zero.

$$I_{1c} = C \frac{dV_C}{dt} = C \frac{d}{dt} (V_0 \cos \omega t) = -C V_0 \omega \sin \omega t.$$

If the insulator in the capacitor is perfect, there is no conduction current there but only displacement current.

$$\begin{aligned} I_{2d} &= \int_S \frac{\partial \mathbf{D}}{\partial t} \cdot d\mathbf{s} = \int_A \left[\frac{\partial}{\partial t} \left(\hat{\mathbf{y}} \frac{\epsilon V_0}{d} \cos \omega t \right) \right] \cdot (\hat{\mathbf{y}} ds) \\ &= -\frac{\epsilon A}{d} V_0 \omega \sin \omega t = -C V_0 \omega \sin \omega t \end{aligned}$$

Even though the displacement current does not transport free charges, it behaves like a real current.

$$I_{1c} = I_{2d} = I_{3c}$$

If the wires have finite conductivity σ_w then the displacement vector is not zero inside the wire and there would be also a displacement current component.

$$I_1 = I_{1c} + I_{1d} \qquad I_3 = I_{3c} + I_{3d}$$

If the insulator in the capacitor is not perfect and has a small conductivity σ_d , there would be also a conduction current besides the displacement one.

$$I_2 = I_{2c} + I_{2d}$$

In any case, the currents in wires and capacitor remain equal

$$I_1 = I_2 = I_3$$

Example – Displacement Current in a good conductor.

The conduction current flowing through a wire with conductivity $\sigma = 2 \times 10^7$ S/m and relative permittivity $\epsilon_r = 1$ is given by $I_c = 2 \sin \omega t$ (mA). If $\omega = 10^9$ rad/s, find the displacement current.

Solution: The conduction current $I_c = J A = \sigma E A$, where A is the cross section of the wire. Hence,

$$E = \frac{I_c}{\sigma A} = \frac{2 \times 10^{-3} \sin \omega t}{2 \times 10^7 A} = \frac{1 \times 10^{-10}}{A} \sin \omega t \quad (\text{V/m})$$

Application of

$$I_d = \int_S \mathbf{J}_d \cdot d\mathbf{s} = \int_S \frac{\partial \mathbf{D}}{\partial t} \cdot d\mathbf{s}$$

with $D = \epsilon E$, leads to  next slide

Example – Displacement Current Density in a good conductor.

$$\begin{aligned} I_d &= J_d A = \epsilon A \frac{\partial E}{\partial t} = \epsilon A \frac{\partial}{\partial t} \left(\frac{1 \times 10^{-10}}{A} \sin \omega t \right) \\ &= \epsilon \omega \times 10^{-10} \cos \omega t = 0.885 \times 10^{-12} \cos \omega t \quad (\text{A}) \end{aligned}$$

where $\omega = 10^9$ rad/s and $\epsilon = \epsilon_0 = 8.85 \times 10^{-12}$ F/m.

Recall that: $I_c = 2 \sin \omega t$ (mA)

Note that I_c and I_d are in phase quadrature (90° phase shift between them). Also, I_d is about nine orders of magnitude smaller than I_c , which is why the displacement current usually is ignored in good conductors.

Example – Displacement Current Density in a poor conductor.

A poor conductor is characterized by a conductivity $\sigma = 100$ (S/m) and permittivity $\epsilon = 4 \epsilon_0$.

At what angular frequency ω is the amplitude of the conduction current density \mathbf{J} equal to the amplitude of the displacement current density \mathbf{J}_d ?

$$\text{Assume } 1 \text{ A/m}^2: \quad J_c = \sigma E = \sin(\omega t)$$

$$E = \frac{J_c}{\sigma} = 10^{-2} \sin(\omega t)$$

$$J_d = \epsilon \frac{\partial E}{\partial t} = 4\epsilon_0 \omega \times 10^{-2} \times \cos(\omega t)$$

$$|J_c| = |J_d| \quad \longrightarrow \quad 1 = 4 \times 8.854 \times 10^{-12} \times \omega \times 10^{-2}$$

$$\omega = \frac{1}{4 \times 8.854 \times 10^{-14}} = 2.82 \times 10^{12} \frac{\text{rad}}{\text{s}}$$

$$f = \frac{\omega}{2\pi} = 449.6 \text{ GHz}$$